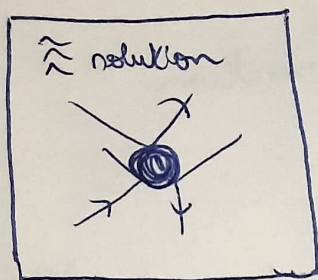


Mon - sun - June 2022

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- Lecture 1a : Slides on active matter - Introduction (from course materials)
- Lecture 1b :
 - Brownian motion : Langevin equation - $\langle V^2 \rangle$ - equipartition - MSD - Stokes-Einstein skipping the calculations.
 - Introduce ABP's conceptually, including equation of motion
- Lecture 2a : ABP's : motion of a single ABP
result for MSD, effective diffusion coefficient
- 2b . Collective motion of ABP's : Phenomenology, MIPS, overview of results (key to ^{more} success in some experiment)
(if there is time) : ABP's in a cell model
- Exercise Class :
 - Introduce Euler-Maruyama for ABP's (note: update slides to reflect lecture of 2 ...)
 - Write single ABP code and compute MSD
 - Let people play with Browser.py collective code

Lecture 1b: Brownian motion (ask for student background)



- Consider:
- particle with radius R , mass m
 - subject to constant collisions with H_2O molecules, on time scales of $\sim 10^{-14}$ s
 - random, very fast -
 - densely matched (to simplify)

Equations of motion:

$$m \frac{d\vec{V}}{dt} = \vec{F}_{\text{tot}} = -\zeta \vec{V} + \vec{f}(t) \quad \text{Langevin equation}$$

↳ Stokes drag: $\zeta = 6\pi\eta R$

$\vec{f}(t)$: random stochastic force: $\langle \vec{f}(t) \rangle = 0$

- zero on average
- no time correlation

$$\langle \vec{f}(t) \cdot \vec{f}(t') \rangle = 2d\gamma \delta(t-t')$$

< > statistical average

Stochastic ODE: we can solve this, e.g. (not focus here)

$$\vec{V}(t) = \vec{V}(0) e^{-t\zeta/m} + \frac{1}{m} \int_0^t e^{-(t-k')\zeta/m} \vec{f}(k') dk'$$

In particular, we can now calculate:

$$\langle \vec{V}(t) \rangle = \langle \vec{V}(0) \rangle e^{-t\zeta/m} + 0 = 0$$

mean velocity also 0 on average $\tau = \frac{m}{\zeta}$ $\langle \vec{f}(k') \rangle = 0$ going nowhere on average

$$\langle V(t)^2 \rangle = \langle V(t) \cdot V(t) \rangle = \dots \text{shot for } 1\mu\text{m colloid}$$

$$= V(0)^2 e^{-2t\zeta/m} + \frac{\gamma}{m\zeta} (1 - e^{-2t\zeta/m})$$

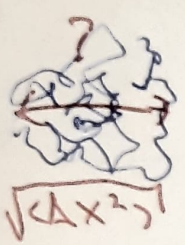
$$\xrightarrow{t \rightarrow \infty} \frac{\gamma}{m\zeta} \text{ constant.}$$

Thermal equilibrium: $\langle T \rangle = \langle V \rangle = \frac{1}{2} kT$

and therefore: $\frac{1}{2} m \langle v^2 \rangle = \frac{1}{2} \frac{\gamma}{\zeta} = \frac{1}{2} k_B T$

or: $\boxed{\gamma = \zeta k_B T}$ *Einstein - diffusion relation*
noise amplitude = friction x temperature

Diffusion:



Random trajectory: How far have I gone?

$$\Delta x(t) = x(t) - x(0) = \int_0^t dt' v(t')$$

$\langle \Delta x(t) \rangle = \underline{0}$ *going nowhere on average*

Calculate the Mean-square displacement:

$MSD(x) = \langle \Delta x^2(t) \rangle$ *square average width of trajectory plot*

= ... relatively involved calculation ...

$$= \frac{\gamma}{\zeta^2} \left[2t + \frac{m}{\zeta} (-2 + 2e^{-\zeta t/m}) \right]$$

$\rightarrow \frac{6\gamma}{\zeta^2} k$ as $t \rightarrow \infty$

Einstein - Stokes relation:

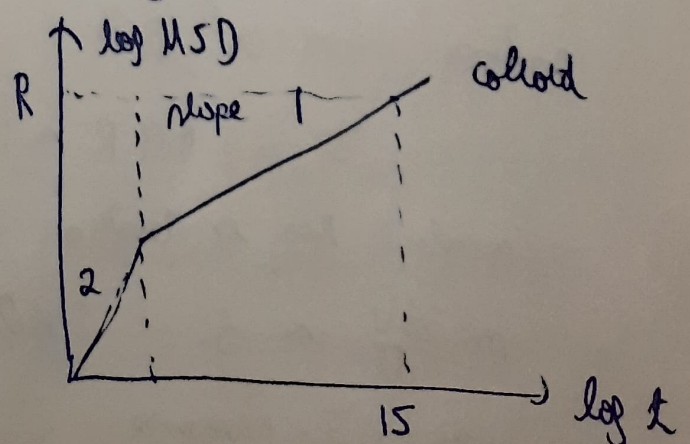
diffusion coefficient

$\gamma = \zeta k_B T \rightarrow MSD(t) = 2 \frac{3 k_B T}{\zeta} t := 2 D t$

Hence: $\boxed{D = \frac{k_B T}{\zeta}}$

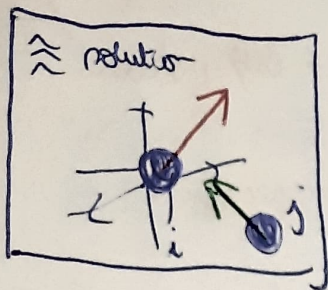
Einstein - Stokes relation

1 μm colloid: $MSD = 6Dt = R^2$
 $D = \frac{k_B T}{6\pi \eta R} \sim 1 \frac{\mu m^2}{s} \Rightarrow \tau = 1 \text{ second}$



Active Brownian motion

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- Consider now a particle either in solution or on a substrate
- could be cell ($\sim 10 \mu\text{m}$), colloid ($\sim 1 \mu\text{m}$) or swimming bacterium ($1 \mu\text{m}$)

- Assume that it is (somehow) driven internally

Biologically $\rightarrow$ crawling cell

$\rightarrow$ swimming using flagella

Chemically $\rightarrow$ Janus particle

$\rightarrow$ electrophoresis / Light + H_2O_2

$\rightarrow$ Magnetic Quincke rollers

$\rightarrow$... (many)

- Equations of motion:

$$m \frac{d\vec{v}_i}{dt} = \vec{F}_i = -\underbrace{\gamma \vec{v}_i}_{\text{friction force}} + \underbrace{\vec{F}_{\text{act}}}_{\text{active force}} + \underbrace{\vec{\eta}_i^T}_{\text{thermal fluctuations } (\equiv \vec{g}(t))} + \sum_{j=1}^N \underbrace{\vec{F}_{ij}}_{\text{pair interactions}}$$

- Simplifications:

1) Overdamped dynamics: Recall $\langle U(x) \rangle \sim e^{-\gamma x / m}$

for $k > T = \frac{m}{\gamma}$, mass term is irrelevant

scaling: $m \sim R^3$

$\gamma = 6\pi\eta R \sim R$

$\tau = \frac{m}{\gamma} \sim R^2 \rightarrow 0$ as $R \rightarrow 0$

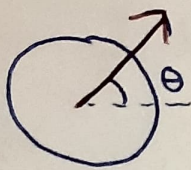
$\Rightarrow$ neglect the acceleration term

$$m \frac{d\vec{v}}{dt} \approx 0$$

divide by γ , rearrange

define: $\frac{\vec{F}_{\text{act}}}{\gamma} = v_0 \hat{m}_i$

active velocity

2)  $\hat{m}_i$ where $\hat{m}_i = (\cos \theta_i, \sin \theta_i)$ is a unit vector (2d version, 3d can also be done)

we will restrict ourselves to motion on a surface (2d)
O.K. for most artificial particles and most cells

Equations of motion for ABP's:

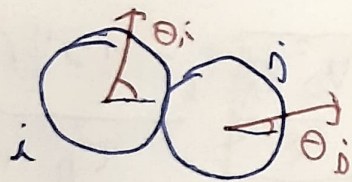
$$\frac{d\vec{r}_i}{dt} = v_0 \hat{m}_i + \frac{1}{\zeta} \sum_{j=1}^N \vec{F}_{ij} + \vec{\tilde{\eta}}_i^T$$

self-propulsion interactions noise

where:
 $\langle \vec{\tilde{\eta}}_i^T(t) \vec{\tilde{\eta}}_j^T(t') \rangle = 4 \delta_{ij} \delta(t-t') \frac{a_B T}{\zeta}$
 2d Stokes-Einstein

Angular dynamics

We have one new variable: θ_i , particle orientation in plane



Need to specify equation of motion too!
moment of inertia

Newton: $I \ddot{\theta}_i = T_i$ torque

$$T_i = -\zeta^R \dot{\theta}_i + \eta^R + \sum_{j=1}^N T_{ij}$$

rotational friction rotational noise pair torques

• Make the same overdamped dynamics assumption: $I \ddot{\theta}_i \approx 0$

$$\frac{d\theta_i}{dt} = \frac{1}{\zeta^R} \sum_{j=1}^N T_{ij} + \tilde{\eta}_i^R$$

$$\langle \tilde{\eta}_i^R(t) \tilde{\eta}_j^R(t') \rangle = 2 \underline{D_R} \delta_{ij} \delta(t-t')$$

• Non-aligning (standard) ABP's

$$T_{ij} = 0$$

rotational diffusion constant

$$\tau_R = \frac{1}{D_R} \text{ reorientation time}$$

Motion of a single ABP

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$$\boxed{\frac{d\vec{r}}{dt} = v_0 \hat{m} + \vec{\eta}^T} \quad \text{and} \quad \boxed{\frac{d\theta}{dt} = \tilde{\eta}^R}$$

$$\langle \vec{\eta}^T(x) \vec{\eta}^T(x') \rangle = 4 D_k \delta(x-x') \quad D_k = \frac{g_R T}{5}$$

$$\begin{aligned} \langle \tilde{\eta}^R(x) \tilde{\eta}^R(x') \rangle &= 2 D_n \delta(x-x') \\ &= \frac{2}{\tau_n} \delta(x-x') \end{aligned}$$

Solve this motion (sketch of derivation):

$$\bullet \frac{d\theta}{dt} = \tilde{\eta}^R \rightarrow \theta(x) = \int_0^x \tilde{\eta}^R(x') dx' \quad \text{formal solution}$$

Can calculate $\hat{m}(x) = (\cos \theta, \sin \theta)$ and its moments

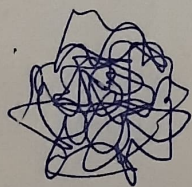
Good result: $\langle \hat{m}(x) \rangle = 0$

$$\langle v_0 \hat{m}(x) \cdot v_0 \hat{m}(x') \rangle = 2 \boxed{\frac{v_0^2 \tau_n}{2}} \frac{e^{-|x-x'|/\tau_n}}{\tau_n}$$

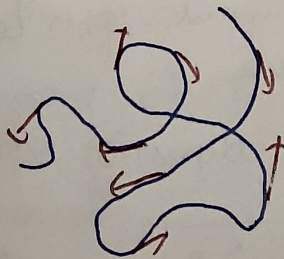
What does that mean?

D_n effective diffusion constant

$\vec{m}(x)$ is time-correlated more with persistence time τ_n



classical random walk



persistent random walk

ABP does persistent kinematics

- persistence time τ_n
- persistence length

$$\boxed{\xi = v_0 \tau_n}$$

$$\bullet \lim \tau_n \rightarrow 0: \langle v_0 \vec{m} \cdot v_0 \vec{m} \rangle \rightarrow 2 \boxed{\frac{v_0^2 \tau_n}{2}} \delta(x-x')$$

normal random walk

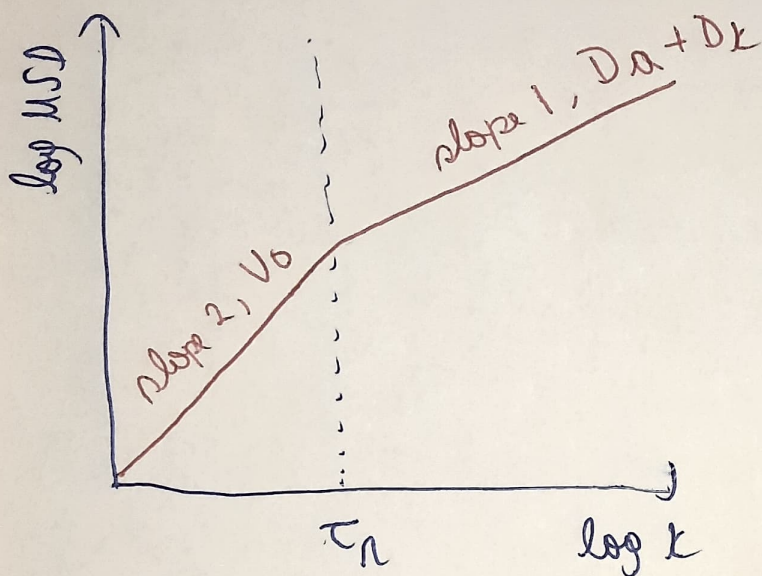
$$\boxed{\frac{g_R T_{eff}}{5}}$$

effective active temperature

Can calculate the MSD here as well;

$$\text{MSD}(t) = \langle |\vec{r}(t) - \vec{r}(0)|^2 \rangle = \dots$$

$$\text{MSD}(t) = 4 D_k t + 2 V_0^2 \tau_n [t - \tau_n (1 - e^{-t/\tau_n})]$$



• for $t \ll \tau_n$

$$\text{MSD}(t) \simeq V_0^2 t^2$$

ballistic straight motion

• for $t \gg \tau_n$

$$\text{MSD}(t) \simeq 4 [D_k + D_a] t$$

behaves like thermal particle, but with effective active temperature!

$$\begin{aligned} D_a &= \frac{V_0^2 \tau_n}{2} \\ &= \frac{k_B T_{\text{eff}}}{\zeta} \end{aligned}$$

Exercise class:

- Numerically integrate equations of motion for single ABP using Euler-Maruyama algorithm
- Compute MSD numerically.